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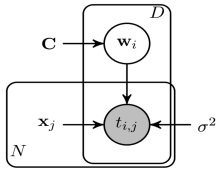
1: UT Austin, 2: Stanford

## Introduction

- Goal: Sequential estimation of factors for Probabilistic PCA
- Lot of prior work factors for deterministic PCA, including sparse variants
- For PPCA, factors are estimated all at once as a subspace
- Sequential estimation benefits include better scalability, runtime model selection, and interpretation of individual factors as directions maximizing variance while retaining the capability to incorporate rich prior structure
- Idea: Use recent results for information projection to restrict support of subsequent factors.
- We present empirical results on fMRI datasets to illustrate interpretability and performance in terms of variance explained.

## Background

- First principal component:
 
$$\max_{\|w\|_2=1} w^\top \Sigma w$$
- Deflation (remove effect of previous component(s)):
 
$$\Sigma_{i+1} = \Sigma_i - w_i w_i^\top \Sigma_i w_i w_i^\top$$
- For the data matrix:
 
$$\mathbf{T}_{i+1} = \mathbf{T}_i - \mathbf{x}_i w_i^\top$$
- Probabilistic PCA plate model



- Information Projection of a density  $p$  onto the set of all densities on  $X$ :

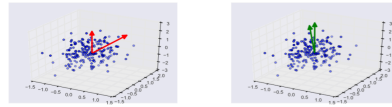
$$KL(q||p) = \int_{x \in X} q(x) \log \frac{q(x)}{p(x)} dx$$

- Variational characterization of restriction of density  $p$ : Information projection is equivalent to domain restriction [1].

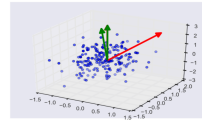
## Deflation for PPCA

Motivating example:

$$\mathbf{W} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}, \mathbf{x}_k \sim \mathcal{N}(\mathbf{0}, \mathbf{I}), \mathbf{e}_n \sim \mathcal{N}\left(\mathbf{0}, \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}\right)$$



(a) Ground Truth (b) Estimated model



(c) Combined Plot

## Variational EM

- Energy function viewpoint of the EM

$$\mathcal{F}(q(\mathbf{W}), \Theta) = -KL(q(\mathbf{W})||p(\mathbf{W}|\mathbf{T}; \Theta)) + \log p(\mathbf{T}; \Theta)$$

$$\text{E-step: } \max_q \mathcal{F}(q(\mathbf{W}), \Theta),$$

$$\text{M-step: } \max_{\Theta} \mathcal{F}(q(\mathbf{W}), \Theta).$$

- Modify the variational E step to restrict support of factors by information projection
- For Gaussian case, E-step equations are

$$\Sigma_i^{-1} = P_{\mathcal{M}_i^{(i-1)}} \left( \frac{1}{\sigma^2} (\mathbf{X}_{\cdot, i}^\top \mathbf{X}_{\cdot, i} \mathbf{I} + \mathbf{C}^{-1}) \right) P_{\mathcal{M}_i^{(i-1)}},$$

$$\mathbf{m}_i = \frac{1}{\sigma^2} \Sigma_i P_{\mathcal{M}_i^{(i-1)}} \mathbf{Z}_i^\top \mathbf{X}_{\cdot, i}.$$

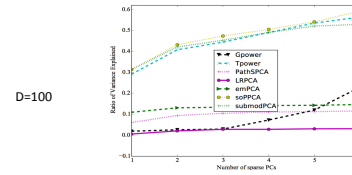
## Sparse PPCA

- Information projection can be used to enforce sparsity as well [2]. The support selection set function is submodular.
- For orthogonal sparse PPCA, we can do project onto a sparse set orthogonal to already chosen factors.
- This can be shown to be equivalent to doing iterated projections.
- Support selection optimization function is written as

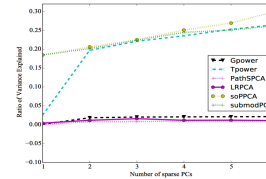
$$\max_{\mathcal{S} \in \mathcal{S}_{k_i}} (P_{\mathcal{S}} \mathbf{r}_i)^\top (P_{\mathcal{S}} \Sigma_i^{-1} P_{\mathcal{S}})^{-1} (P_{\mathcal{S}} \mathbf{r}_i) - \log \det P_{\mathcal{S}} \Sigma_i^{-1} P_{\mathcal{S}}.$$

## Results

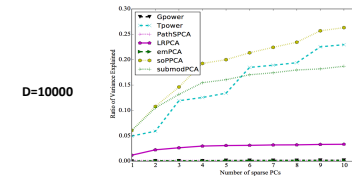
- We compare on fMRI datasets against several known sparse PCA methods. Of special note is comparison against emPCA and submodPCA both of which use naive deflation



D=100



D=1000



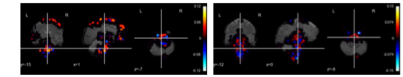
D=10000

## Deterministic reductions

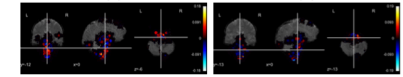
- The Orthogonal PPCA reduces to standard deterministic PCA if  $C=I$
- The Sparse PPCA reduces to Truncated Power Method with Orthogonal projection deflation.

## Brain plots

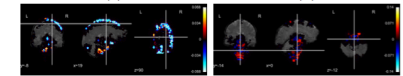
Brain plots indicating extraction of motion artifacts from resting state data.



(a) (b)



(c) (d)



(e) (f)

## References

- [1] Oluwasanmi Koyejo, Rajiv Khanna, Joydeep Ghosh, and Poldrack Russell. On prior distributions and approximate inference for structured variables. In NIPS, 2014.
- [2] Rajiv Khanna, Joydeep Ghosh, Russell A. Poldrack, and Oluwasanmi Koyejo. Sparse submodular probabilistic PCA. In AISTATS 2015